

Towards Automated Analysis of Belousov-Zhabotinsky Reactions in a Petri Dish by Membrane Computing using Optic Flow

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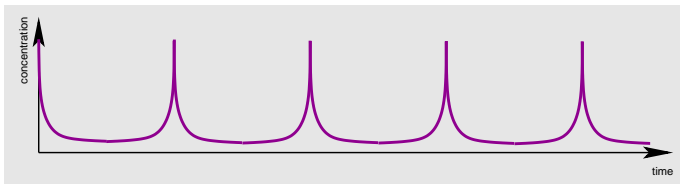
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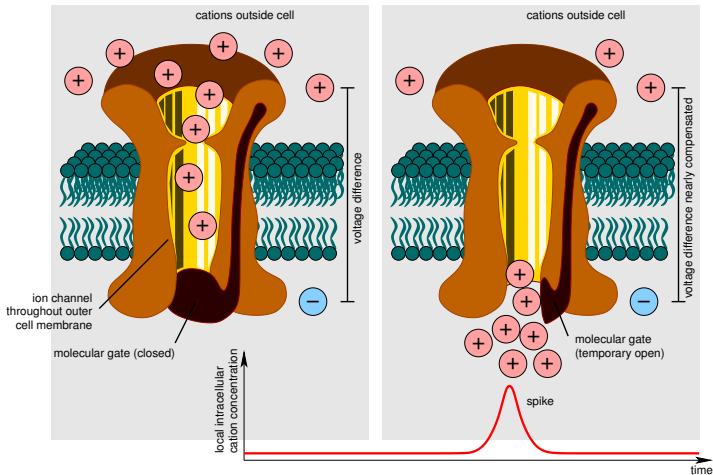
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Spiking Oscillations in Time and Space

- Widespread medium for *signal transduction* in biology
- Highly *energy-efficient*
- Oscillation course easy to generate
- Number and/or periodicity of spikes expresses information
- Utilisation of *frequency encoding* in biology
- Outstanding robustness against environmental perturbations and weakening of the signal when spreading out in space

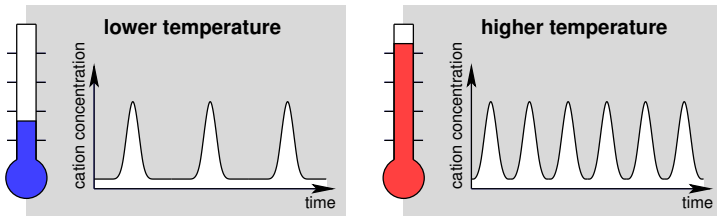


Example: Ion Channel-Based Temperature Reception



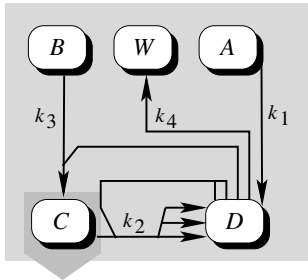
Transient Receptor Potential (TRP) channels highly conserved

Ion Channel Acting as Thermosensor



- With increasing temperature, diminished electrical forces to open molecular gate within TRP channel
- Increasing temperature results in higher frequency of spiking oscillation (warm sensor)
- *Frequency encoding* of temperature within physiological range but non-linear mapping between temperature and oscillation frequency

Reaction Scheme: Ion Channel as Thermosensor



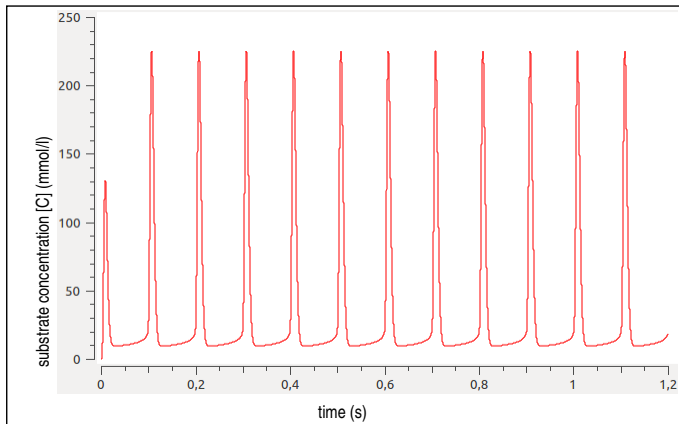
Species identifiers

- A** inositol triphosphate (IP3)
- B** calcium ions outside cell
- C** calcium ions inside cell (*output*)
- D** permeability of ion channel
expressed by spatial protein structure
- W** .. waste (excess of open-gate *D* structure)



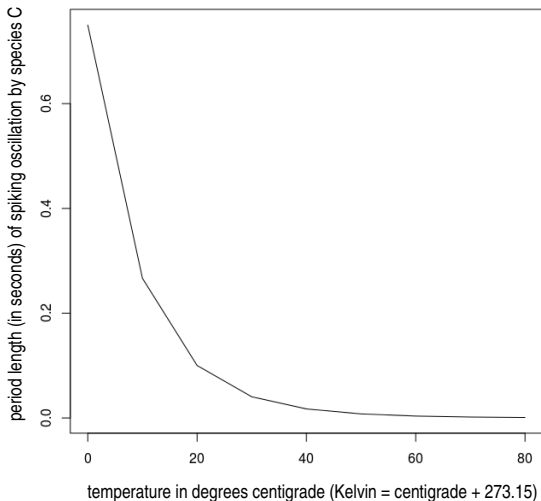
- *Suppliers* **A** (second messenger IP3) and **B** (Ca²⁺) fuel the oscillator
- Self-amplifying effect attracts more and more **B** to *enter* the cell leading to fast increase of **C** (positive feedback induces spike)
- *Short-time self-amplification*, afterwards *collapsing* due to lack of **B**
- As soon as enough **B** accumulated, *next spike* generated
- Resembles operation principle of *Brusselator*

Spiking Behaviour of Thermosensor



- At **20°C** (293.15K) spiking period length of **100ms**
- Higher temperature shortens period length
- Thermosensor maps temperature into period length

Period Length subject to Environmental Temperature



Impetus of Spiking Oscillations in Biology

Found in numerous signal transduction schemes:

- *Ion channels* as sensors
- *Calcium oscillations* for intracellular signal propagation

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⇒ **Biological systems with common principle of operation**

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⇒ ***Belousov-Zhabotinsky* reaction scheme in a Petri dish**

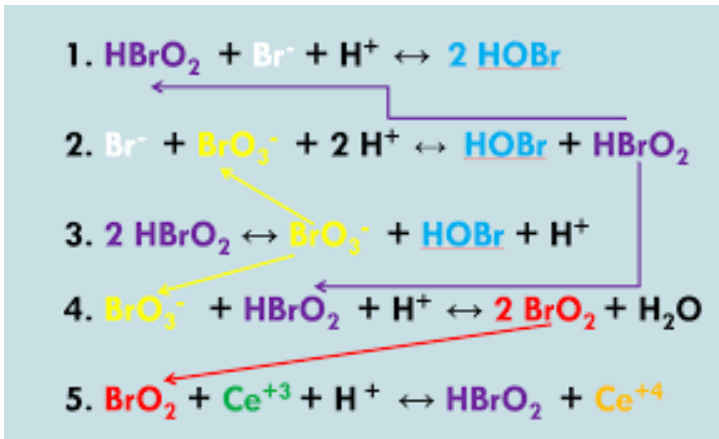
Belousov-Zhabotinsky Reaction Scheme in Petri Dish

- Dissipative auto-catalytic loop of two key processes
- **Forward process** generates molecular *bromine* (BrO_2 , brown colour)
- Feedback process consumes bromine to release bromide ions (Br^- , grey or white colour)
- Injection of *ferroin, cerium or other indicator* acting as reductant to initiate oscillation
- Expanding *concentric rings* out of an *oscillatory spot*



www.wikipedia.org

Belousov-Zhabotinsky Reaction Network

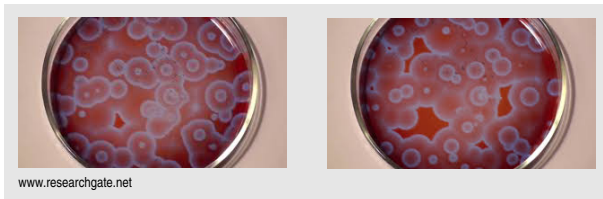


www.univr.it

Processes interact within positive feedback loop (Cerium injection).

Analysis of Belousov-Zhabotinsky Reactions

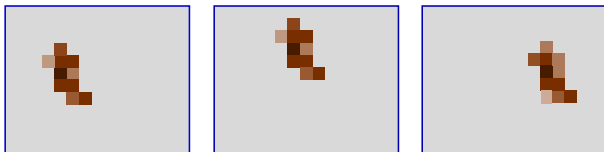
- *Videos* and *image sequences* document oscillatory behaviour
- Expanding concentric rings indicate run of the reactions
- Ratio of initial concentrations together with environmental factors like temperature determine oscillation frequency
- Simple *in-vitro* model for chemical *frequency encoding*
- Huge amount of video and image data available



⇒ Aim: Automated analysis for identification and localisation of oscillatory spots and oscillation frequency in each spot

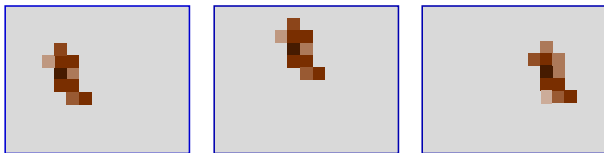
Application of Membrane Computing

- Groups of adjacent *pixels* in similar colour act as *particles*



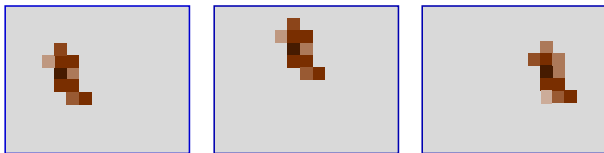
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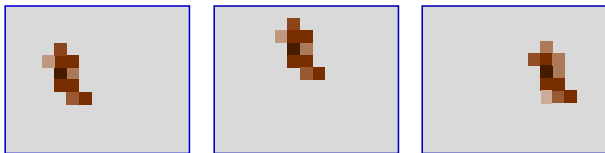
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⇒ Mathematical techniques for analysis of image sequences (Optic Flow) opens a new application of membrane computing.

Automated BZ Reaction Analysis

Goals

- Identify and count oscillatory spots
- Determine velocity of expanding concentric rings for each spot



[1]

Image Sequence Characteristics

What is missing?

- Image sequence of liquids \Rightarrow constant illumination?
- No static background \Rightarrow motion isolation?

What do we have?

- Small motion
- Neighbouring points move in almost the same direction
 - ... but with slight intersection of the expanding concentric rings
- Stationary oscillatory spots
- Huge homogeneous areas

\Rightarrow Motion segmentation

Motion Detection and Segmentation

Goal

- Distinct motion areas around different oscillatory spots

Characteristics of a Method that would benefit us

- Works without foreground/background distinction
- Deals with changing illumination
- Can handle homogeneous, expanding areas
- Filters superposition of motion
- Robust to noise

⇒ Looking for an egg-laying, milk-bearing woolly sow

Motion Detection and Segmentation

... with resulting vector fields

Method Overview

- Image difference
 - Needs homogeneous motion areas/rigid bodies
 - Extremely sensitive to noise
- Block matching
 - Divide image into macro blocks and estimate homogeneous motion for each block
 - Erroneous method
 - Can erase critical motion areas
- Optic Flow

Optic Flow

Characteristics

Advantages

- No fore- and background distinction needed
- Methods with partial robustness to noise exist
- Computes motion direction and velocity for each point, influenced by neighbouring points

Disadvantages

- Sensitive to variations in illumination
- Difficulties with homogeneous areas
- Sensitive to superposition of motions

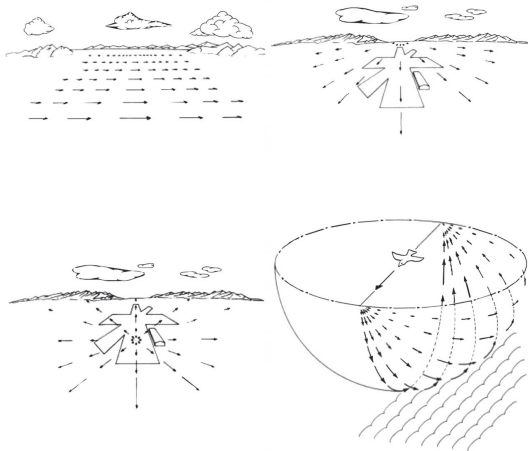
Optic Flow

Apparent motion of brightness patterns^(Horn and Schunck [2]) . . .

- Usually computed on two dimensional grey-value (brightness intensities) sequences
- Results in a vector field

Optic Flow applications:
(also holds for other motion segmentation methods)

- Autonomous driving, robot navigation and interaction with the environment (stereo vision)
- Image compression and reconstruction
- Tracking (e.g. optical computer mice)



James J. Gibson, The perception of the visual world [3].

Brightness Constancy Assumption

Constant Brightness Patterns

- Brightness of points in a pattern is expected to be constant

$$E(x(t), y(t), t) = C \text{ (constant)} \Rightarrow \frac{dE}{dt} = 0$$

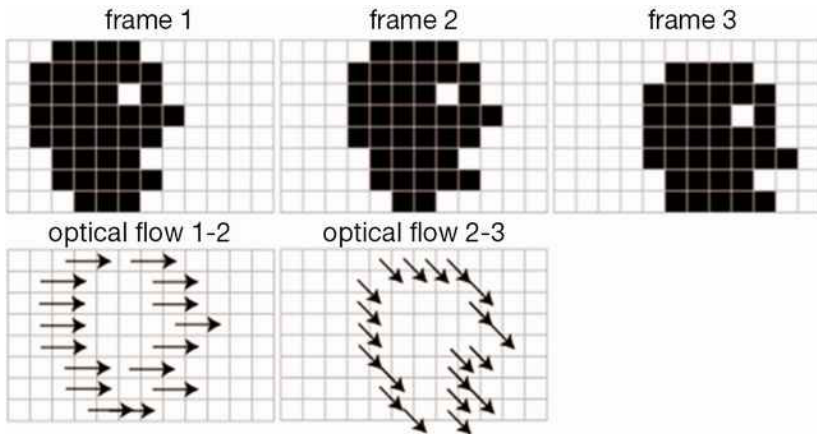
- It follows a linear equation with two unknowns (u, v)

$$E_x \cdot u + E_y \cdot v + E_t = 0$$

$$u = \frac{dx}{dt}, v = \frac{dy}{dt}$$

⇒ Second constraint for motion vector determination needed

Brightness Constancy Assumption



Example for a moving brightness pattern. [4]

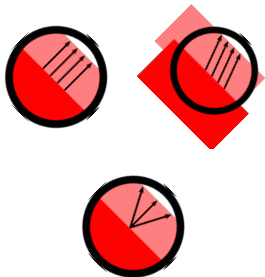
Aperture Problem

Barberpole Illusion

- First observed and evaluated by Hans Wallach in 1935 [5]



Barberpole [6]



- Various concepts for the second constraint we will use the proposal by Horn and Schunck [2]

Second Constraint

Problem

- each point moves for itself \Rightarrow recovering motions will be impossible

Solution

- assume that neighbouring points undergoing similar motions as the point itself and the motion field varies smoothly everywhere

$$\nabla^2 u = 0 \text{ and } \nabla^2 v = 0$$

- penalise deviation from expected smooth variation

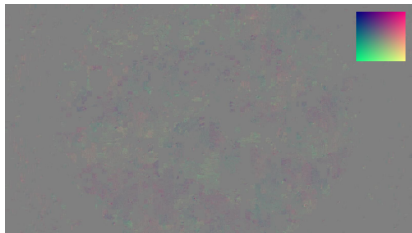
Euler-Lagrange Equation

Minimise the Error

$$\varepsilon = \int \int \alpha^2 \cdot \varepsilon_1^2 + \varepsilon_2^2 \, dx \, dy$$

- Minimising the sum of the first and second constraint and a weighting factor α^2
- Equation will be transformed into a linear equation system and solved with a fixed point iteration scheme

Optic Flow Results



- Optic Flow motion vector field of BZ reaction sequence

Next Steps

- apply a filter to the Optic Flow result
- determine sources of the vector field

Recovering the Motion

Expected Motion Field

- Same velocities around an oscillatory spot
- Motion directions vary only slightly
 - ⇒ Expanding concentric rings
- all motion leading away from a common central point

Filter Expectation

- Recover the motion that outweighs an area
- Robustness against outliers
- Determine and preserve sinks

Smoothing Filter

$\vec{V}_{m,n} = (\vec{V}_{t,x}, \vec{V}_{t,y})$ with $2 \cdot m \cdot n$ elements

$V_{t,x}(p, q), V_{t,y}(p, q) \in \mathbb{R}$ with $p = 1, \dots, n$ and $q = 1, \dots, m$

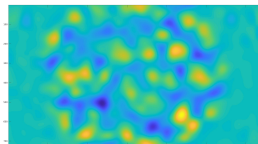
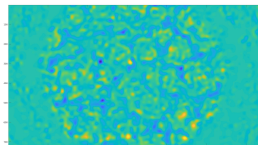
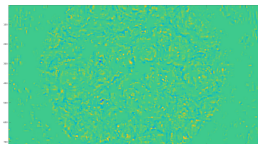
$$S = \begin{pmatrix} s_{1,1} & s_{2,1} & s_{3,1} \\ s_{1,2} & s_{2,2} & s_{3,2} \\ s_{1,3} & s_{2,3} & s_{3,3} \end{pmatrix} = \begin{pmatrix} \frac{1}{12} & \frac{1}{6} & \frac{1}{12} \\ \frac{1}{6} & 0 & \frac{1}{6} \\ \frac{1}{12} & \frac{1}{6} & \frac{1}{12} \end{pmatrix}$$

$$V_{t+1,x}(p, q) = \sum_i \sum_j s_{i+2,j+2} \cdot V_{t,x}(p+i, q+j) \quad \text{with } i, j \in \{-1, 0, 1\}$$

for $V_{t+1,y}(p, q)$, respectively

Resulting Flow Field

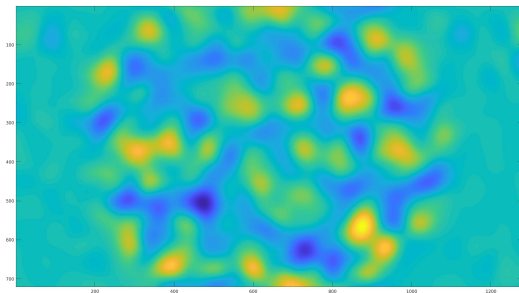
- $10\times$, $100\times$, $1000\times$ filter applications
- constraint to determine filter applications automatically



Vector Field Sources

Determine Sources and Sinks

- Divergence of a vector field results in a scalar field
- Each scalar represents how sourcish/sinkish a value is



Future Prospect

- Finalise the automatic evaluation to receive the number of oscillatory spots and velocity of the concentric rings around them
- Finalise an implementation with self-explaining user interface
- Test different Optic Flow approaches to reduce filter dependency

Thank you very much
for your attention!

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