

A Semantic Investigation of Spiking Neural P Systems

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Aim and Contribution

- We present a **denotational semantics** $\llbracket \cdot \rrbracket$ for a language \mathcal{L}_{SNP} inspired by the **spiking neural P (SN P) systems** [Ionescu, Păun and Yokomori - 2006]
 - At syntactic level \mathcal{L}_{SNP} provides constructions for specifying: neurons and synapses, rules with time delays
 - The denotational semantics $\llbracket \cdot \rrbracket$ for \mathcal{L}_{SNP} is designed with **metric spaces** and **continuations**
- We provide a **Haskell implementation of $\llbracket \cdot \rrbracket$**

`http://ftp.utcluj.ro/pub/users/gc/eneia/cmc19`

Aim and Contribution

- **SN P systems** - a class of P systems **inspired from the way neurons communicate by means of spikes** [Păun - 2007]
 - Equivalent in computational power to Turing machines
 - Able to solve NP-complete problems in polynomial time
- We investigate the behavior of SN P systems using methods specific of **programming languages semantics**
 - **Syntax of \mathcal{L}_{SNP}** is specified in BNF
 - \mathcal{L}_{SNP} constructions are called **statements** or **programs**
 - Semantics of \mathcal{L}_{SNP} is described in **denotational style**

Aim and Contribution

- Our **denotational semantics** $\llbracket \cdot \rrbracket$ describes accurately
 - The **structure of SN P systems**: neurons, synapses, spikes
 - The **behavior of SN P systems**:
 - Time delays between firings and spiking
 - Non-deterministic behavior and synchronized functioning
- $\llbracket \cdot \rrbracket$ is the first denotational (compositional) semantics for this combination of concepts, specific of **SN P systems**

Principles of Denotational Semantics (mathematical or Scott-Strachey semantics)

- Language constructions *denote* values from a *mathematical domain* of interpretation

$$\llbracket \cdot \rrbracket : \mathcal{L} \rightarrow \mathbf{D}$$

- *Definitions are compositional*

$$\llbracket \dots x_1 \dots x_2 \dots \rrbracket = \dots \llbracket x_1 \rrbracket \dots \llbracket x_2 \rrbracket \dots$$

- Various options in designing \mathbf{D} and $\llbracket \cdot \rrbracket$ for a given \mathcal{L}
 - Classic (order-theoretic) domains vs metric spaces
 - Direct semantics, continuations

Metric Spaces vs Order-Theoretic Domains

- The purpose of **domain theory** is to give models for spaces on which to define computable functions [Scott - 1982]
- In **classic domains** (order-theoretic domains)
 - One works with **least fixed points** of continuous functions
 - Not all elements are comparable, **the order is partial**
- **Metric spaces** employ additional information
 - One can (compare and even) **measure the distance** between any two elements of a metric space
 - Contracting functions on complete metric spaces have **unique fixed points (Banach's theorem)**

Metric Spaces vs Order-Theoretic Domains

- **Domain theory** was initiated by [Scott - 1976, Scott - 1982]
 - Scott's key construction - a solution of the 'equation'

$$\mathbf{D} \cong \mathbf{D} \rightarrow \mathbf{D}$$

- We offer a **semantic description of SN P systems** based on a **domain of continuations**

$$\mathbf{D} \cong \mathbf{K} \rightarrow \mathbf{K}$$

$$\mathbf{K} \cong \dots \mathbf{D} \dots$$

- Following [De Bakker and De Vink - 1996] we employ the mathematical methodology of **metric semantics**
 - Traditional (direct) concurrency semantics may not work for the complex interactions specific of MC and SN P systems

Continuation Semantics for Concurrent Languages

- In **Continuation-Passing Style (CPS)** control is passed explicitly in the form of continuations [Appel - 2007]
- We need a domain of **continuations** which **can store computations** (between firings and spikings) in **CSC style** [Todoran - 2000, Ciobanu & Todoran - 2014]

$$\mathbf{D} \cong \mathbf{K} \rightarrow \mathbf{K}$$

$$\mathbf{K} \cong \dots \mathbf{D} \dots$$

- In previous work we investigated **MC concepts** by using a simple domain of continuations

G. Ciobanu and E.N. Todoran, Denotational Semantics of Membrane Systems by using Complete Metric Spaces, *Theor. Comput. Sci.*, 2017.

Syntax of \mathcal{L}_{SNP}

Definition (Syntax of \mathcal{L}_{SNP})

- (a) (Statements) $x(\in X) ::= a \mid \text{send}(y, \xi) \mid x \parallel x$
 $y(\in Y) ::= a \mid y \parallel y$ (obviously, $Y \subseteq X$)
- (b) (Rules) $r(\in Rs) ::= r_\epsilon \mid \varrho, r$
 $\varrho(\in R) ::= E/w \rightarrow x; t \mid w \rightarrow \lambda,$
(E is a regular expression over O, $w \neq []$, $t \geq 0$, $t \in \mathbb{N}$)
- (c) (Neuron declarations)
 $d(\in ND) ::= \text{neuron } N \{ r \mid \xi \}$ $D(\in NDs) ::= d \mid d, D$
- (d) (Programs) $\rho(\in \mathcal{L}_{SNP}) ::= D, x$ (*x executed by first neuron in D*)

- $(a \in) O$ - alphabet of spikes/objects (several types of spikes)
- $(N \in) Nname$ - set of neuron names
- $(w \in) W = [O]$ - set of multisets over O
- $(\xi \in) \Xi = \mathcal{P}_{fin}(Nname)$ - finite sets of neuron names
- Extended rules - a statement x is able to produce more than one spike
- $\text{send}(y, \xi)$ is specific of \mathcal{L}_{SNP}
 (Instead of W and Ξ we could use O^* and $Nname^*$)

An \mathcal{L}_{SNP} program and its intuitive behavior

$$\rho_1 = (D_1, x_1)$$

$$x_1 = \text{send}(\langle a^{2k-1} \rangle, \{N_1\}) \parallel \text{send}(a, \{N_3\})$$

$$D_1 = \text{neuron } N_0 \{ r_\epsilon \mid \{N_1, N_2, N_3\} \},$$

$$\text{neuron } N_1 \{ a^+ / [a] \rightarrow a; 2 \mid \{N_2\} \},$$

$$\text{neuron } N_2 \{ [a^k] \rightarrow a; 1 \mid \{N_3\} \},$$

$$\text{neuron } N_3 \{ [a] \rightarrow a; 0 \mid \{N_0\} \}$$

$$\{(N_0, []), (N_1, [a, a, a]), (N_2, []), (N_3, [a])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a, a, a]), (N_2, []), (N_3, [])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a, a, a]), (N_2, []), (N_3, [])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$$

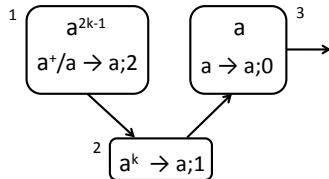
$$\Rightarrow \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a]), (N_2, [a, a]), (N_3, [])\}$$

$$\Rightarrow \{(N_0, [a]), (N_1, [a]), (N_2, [a, a]), (N_3, [])\}$$

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$$\Rightarrow \{(N_0, [a, a]), (N_1, []), (N_2, [a]), (N_3, [])\}$$



[Ionescu, Păun and Yokomori – 2006]
SN P system Π_1

$$\Leftarrow k = 2$$

The output neuron N_3 spikes in steps 2 and 10

The number computed by this \mathcal{L}_{SNP} program is

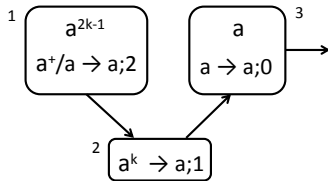
$$3k + 2 = 8$$

(same as in [Ionescu, Păun and Yokomori - 2006])

Two behaviorally equivalent \mathcal{L}_{SNP} programs

$\rho_1 = (D_1, x_1)$
 $x_1 = \text{send}(\langle a^{2k-1} \rangle, \{N_1\}) \parallel \text{send}(a, \{N_3\})$
 $D_1 =$ neuron $N_0 \{ r_\epsilon \mid \{N_1, N_2, N_3\} \}$,
 neuron $N_1 \{ a^+ / [a] \rightarrow a; 2 \mid \{N_2\} \}$,
 neuron $N_2 \{ [a^k] \rightarrow a; 1 \mid \{N_3\} \}$,
 neuron $N_3 \{ [a] \rightarrow a; 0 \mid \{N_0\} \}$

$\rho'_1 = (D'_1, x'_1)$
 $x'_1 = \text{send}(\langle a^{2k-1} \rangle, \{N_1\}) \parallel \text{send}(a, \{N_3\})$
 $D'_1 =$ neuron $N_0 \{ r_\epsilon \mid \{N_1, N_2, N_3\} \}$,
 neuron $N_1 \{ a^+ / [a] \rightarrow \text{send}(a, \{N_2\}); 2 \mid \{N_2, N_3\} \}$,
 neuron $N_2 \{ [a^k] \rightarrow \text{send}(a, \{N_3\}); 1 \mid \{N_1, N_3\} \}$,
 neuron $N_3 \{ [a] \rightarrow a; 0 \mid \{N_0\} \}$



[Ionescu, Păun and Yokomori – 2006]
SN P system Π_1

Observables and final semantic domain

[De Bakker and De Vink - 1996]

- Final semantic domain \mathbf{P}, \mathbf{Q} (linear time)

$$(p \in) \mathbf{P} = \mathcal{P}_{nco}(\mathbf{Q}) \quad (q \in) \mathbf{Q} \cong \{\epsilon\} + (\Omega \times \frac{1}{2} \cdot \mathbf{Q})$$

- Set of observables Ω

$$(\omega \in) \Omega = \{\omega \mid \omega \in \mathcal{P}_{nfin}(Nname \times W), \nu(\omega)\}$$

- Nondeterministic choice operator $\oplus : (\mathbf{P} \times \mathbf{P}) \xrightarrow{1} \mathbf{P}$

$$p_1 \oplus p_2 = \{q \mid q \in p_1 \cup p_2, q \neq \epsilon\} \cup \{\epsilon \mid \epsilon \in p_1 \cap p_2\}$$

Remark

\oplus is associative, commutative and idempotent

Computations and continuations

[America and Rutten - 1989]

$$(\varphi \in) \mathbf{D} \cong \mathbf{K} \xrightarrow{1} \mathbf{K}$$

$$(\phi \in) \mathbf{Den} = \{d_0\} + \mathbf{D}$$

$$(\kappa \in) \mathbf{K} = \Gamma \xrightarrow{1} \mathbf{P}$$

- Continuations

$$(\gamma \in) \Gamma = \{\Sigma\}$$

- Configurations

$$(\sigma \in) \Sigma = \mathbf{Open} + \mathbf{Closed}$$

- States (of neurons)

$$\mathbf{Open} = \Xi \times W$$

$$\mathbf{Closed} = \Xi \times W \times \mathbb{N} \times W \times \frac{1}{2} \cdot \mathbf{D}$$

$$\{\Sigma\} \stackrel{not.}{=} \Xi \times (Nname \rightarrow \Sigma) \quad - \text{Multisets / Bags (of states)}$$

$$[\gamma \mid N \mapsto \sigma] \quad - \text{Update (state of neuron } N \text{ in } \gamma \text{ with } \sigma)$$

Continuation semantics for parallel composition

Definition (Semantics of \parallel in continuation semantics)

We define $\parallel: (\mathbf{D} \times \mathbf{D}) \xrightarrow{1} \mathbf{D}$, $\lfloor: (\mathbf{D} \times \mathbf{D}) \xrightarrow{1} \mathbf{D}$ by:

$$\varphi_1 \parallel \varphi_2 = \lambda\kappa. \lambda\gamma. ((\varphi_1 \lfloor \varphi_2)(\kappa)(\gamma) \oplus (\varphi_2 \lfloor \varphi_1)(\kappa)(\gamma))$$

$$\varphi_1 \lfloor \varphi_2 = \varphi_1 \circ \varphi_2 \quad (' \circ ' \text{ is function composition operator})$$

Remarks

- \parallel and \lfloor are well-defined and nonexpansive in both args
- \lfloor is associative
- \parallel is commutative (because \oplus is commutative)



Semantics of \mathcal{L}_{SNP} statements

Definition (Denotational semantics $\llbracket \cdot \rrbracket : X \rightarrow Alpha \rightarrow \mathbf{D}$)

$$\begin{aligned}\llbracket a \rrbracket(\alpha) &= \lambda \kappa . \lambda \gamma . \kappa(\mathit{send}(a, \alpha, \gamma)), \\ \llbracket \mathit{send}(y, \xi) \rrbracket(\alpha) &= \llbracket y \rrbracket(\xi \pitchfork \alpha), \\ \llbracket x_1 \parallel x_2 \rrbracket(\alpha) &= \llbracket x_1 \rrbracket(\alpha) \parallel \llbracket x_2 \rrbracket(\alpha).\end{aligned}$$

- $(\alpha \in)Alpha = Nname \times \Theta$
- $(\theta \in)\Theta = \{\mathit{all}\} \cup \Xi$
- $\pitchfork : (\Xi \times Alpha) \rightarrow Alpha$
 - $\xi \pitchfork (N, \mathit{all}) = (N, \xi)$
 - $\xi \pitchfork (N, \xi') = (N, \xi \cap \xi')$

The operation $send : (O \times Alpha \times \Gamma) \rightarrow \Gamma$

$$\begin{aligned} send(a, (N, all), \gamma) = & \\ & \text{let } \{N_1, \dots, N_i\} = nbs(N, \gamma) \\ & \text{in } [\gamma \mid N_1 \mapsto add(a, \gamma(N_1)) \mid \dots \mid N_i \mapsto add(a, \gamma(N_i))], \\ send(a, (N, \xi), \gamma) = & \\ & \text{let } \{N_1, \dots, N_i\} = nbs(N, \gamma) \cap \xi \\ & \text{in } [\gamma \mid N_1 \mapsto add(a, \gamma(N_1)) \mid \dots \mid N_i \mapsto add(a, \gamma(N_i))] \end{aligned}$$

$$add(a, (\xi, w)) = (\xi, w \uplus [a])$$

$$add(a, (\xi, w, t, w_r, \varphi)) = (\xi, w, t, w_r, \varphi)$$

Compositional reasoning with continuations

Proposition

- (a) $\llbracket x_1 \rrbracket(\alpha_1) \parallel \llbracket x_2 \rrbracket(\alpha_2) = \llbracket x_1 \rrbracket(\alpha_1) \downarrow \llbracket x_2 \rrbracket(\alpha_2) = \llbracket x_2 \rrbracket(\alpha_2) \downarrow \llbracket x_1 \rrbracket(\alpha_1)$
- (b) $\llbracket x_1 \parallel x_2 \rrbracket = \llbracket x_2 \parallel x_1 \rrbracket$
- (c) $\llbracket x_1 \parallel (x_2 \parallel x_3) \rrbracket = \llbracket (x_1 \parallel x_2) \parallel x_3 \rrbracket$

Proof.

Property (a) follows by induction on $size(x_1) + size(x_2)$; note that, in general, $\alpha_1 \neq \alpha_2$. For property (c), let $x_1, x_2, x_3 \in X$, $\alpha \in Alpha$.

$$\begin{aligned}
 \llbracket x_1 \parallel (x_2 \parallel x_3) \rrbracket(\alpha) &= \llbracket x_1 \rrbracket(\alpha) \parallel \llbracket x_2 \parallel x_3 \rrbracket(\alpha) \\
 &= \llbracket x_1 \rrbracket(\alpha) \downarrow \llbracket x_2 \parallel x_3 \rrbracket(\alpha) = \llbracket x_1 \rrbracket(\alpha) \downarrow (\llbracket x_2 \rrbracket(\alpha) \parallel \llbracket x_3 \rrbracket(\alpha)) && \text{[Property (a)]} \\
 &= \llbracket x_1 \rrbracket(\alpha) \downarrow (\llbracket x_2 \rrbracket(\alpha) \downarrow \llbracket x_3 \rrbracket(\alpha)) && \text{[} \downarrow \text{ is associative]} \\
 &= (\llbracket x_1 \rrbracket(\alpha) \downarrow \llbracket x_2 \rrbracket(\alpha)) \downarrow \llbracket x_3 \rrbracket(\alpha) \\
 &= (\llbracket x_1 \rrbracket(\alpha) \parallel \llbracket x_2 \rrbracket(\alpha)) \downarrow \llbracket x_3 \rrbracket(\alpha) = \llbracket x_1 \parallel x_2 \rrbracket(\alpha) \downarrow \llbracket x_3 \rrbracket(\alpha) && \text{[Property (a)]} \\
 &= \llbracket x_1 \parallel x_2 \rrbracket(\alpha) \parallel \llbracket x_3 \rrbracket(\alpha) = \llbracket (x_1 \parallel x_2) \parallel x_3 \rrbracket(\alpha)
 \end{aligned}$$



Semantics of \mathcal{L}_{SNP} programs

Definition (Initial continuation κ_0)

Let $\Psi_{\mathbf{K}} : \text{NDs} \rightarrow \mathbf{K} \rightarrow \mathbf{K}$ be given by

$$\Psi_{\mathbf{K}}(D)(\kappa)(\gamma) = \text{to}_{\Omega}(\gamma) \cdot (\text{ if } \text{halt}_{NS}(\gamma, D) \text{ then } \{\epsilon\} \\ \text{ else } \bigoplus\{\varphi(\kappa)(\gamma') \mid (\varphi, \gamma') \in \text{sched}(\gamma, D)\} \bigoplus \\ \bigoplus\{\kappa(\gamma') \mid (d_0, \gamma') \in \text{sched}(\gamma, D)\})$$

For any $D \in \text{NDs}$, we define $\kappa_0 \in \mathbf{K}$ by $\kappa_0 = \text{fix}(\Psi_{\mathbf{K}}(D))$.

Remark (Time is implicit in our denotational model)

- In SNP systems *functioning is synchronized*
- A *global clock* is assumed; in our model the value of the clock is *given by the number of Ω observable steps* in each \mathbf{Q} execution trace
- $\text{to}_{\Omega} : \Gamma \rightarrow \Omega$ produces an *observable* $\omega \in \Omega$ from a configuration $\gamma \in \Gamma$



Semantics of \mathcal{L}_{SNP} programs - scheduler mapping

$$\| : (\mathbf{Den} \times \mathbf{Den}) \xrightarrow{1} \mathbf{Den}, d_0 \parallel d_0 = d_0, d_0 \parallel \varphi = \varphi, \varphi \parallel d_0 = \varphi, \varphi_1 \parallel \varphi_2 = \varphi_1 \parallel \varphi_2$$

$$sched : (\Gamma \times NDS) \rightarrow \mathcal{P}_{co}(\mathbf{Den} \times \Gamma)$$

$$sched(\gamma, D) = \text{let } \{N_0, \dots, N_m\} = id(\gamma) \\ \text{in } \{(\parallel_{i=0}^m \phi_i, [\gamma \mid N_0 \mapsto \sigma_0 \mid \dots \mid N_m \mapsto \sigma_m]) \\ \mid (\phi_0, \sigma_0) \in schedN(N_0, \gamma(N_0), D), \dots, \\ (\phi_m, \sigma_m) \in schedN(N_m, \gamma(N_m), D)\}$$

$$schedN : (Nname \times \Sigma \times NDS) \rightarrow \mathcal{P}_{co}(\mathbf{Den} \times \Sigma)$$

$$schedN(N, (\xi, w), D) = \text{if } halt_N(N, (\xi, w), D) \text{ then } \{(d_0, (\xi, w))\} \\ \text{else let } r = rules(D, N) \\ \text{in } \{(\llbracket x \rrbracket(N, \text{all}), (\xi, w \setminus w_r)) \\ \mid (E/w_r \rightarrow x; t) \in r, w \in L(E), w_r \subseteq w, t = 0\} \cup \\ \{(d_0, (\xi, w, t - 1, w \setminus w_r, \llbracket x \rrbracket(N, \text{all}))) \\ \mid (E/w_r \rightarrow x; t) \in r, w \in L(E), w_r \subseteq w, t > 0\} \cup \\ \{(d_0, (\xi, [])) \mid (w_r \rightarrow \lambda) \in r, w_r = w\};$$

$$schedN(N, (\xi, w, t, w_r, \varphi), D) =$$

$$\text{if } t = 0 \text{ then } \{(\varphi, (\xi, w_r))\} \text{ else } \{(d_0, (\xi, w, t - 1, w_r, \varphi))\}$$

Semantics of \mathcal{L}_{SNP} programs: fixed-point (compositional) semantics

Proposition (κ_0 is well-defined (Banach))

$\Psi_{\mathbf{K}}(D) \in \mathbf{K} \xrightarrow{\frac{1}{2}} \mathbf{K}$ ($\Psi_{\mathbf{K}}(D)$ is a contraction), for any $D \in NDs$.

Proof.

It suffices to prove the following (for any $D \in NDs, \kappa_1, \kappa_2 \in \mathbf{K}, \gamma \in \Gamma$):

$$d(\Psi_{\mathbf{K}}(D)(\kappa_1)(\gamma), \Psi_{\mathbf{K}}(D)(\kappa_2)(\gamma)) \leq \frac{1}{2} \cdot d(\kappa_1, \kappa_2)$$

We have

$$\begin{aligned} & d(\Psi_{\mathbf{K}}(D)(\kappa_1)(\gamma), \Psi_{\mathbf{K}}(D)(\kappa_2)(\gamma)) \\ & \quad [\text{"to}_\Omega(\gamma)\text{" - step in def. } \Psi_{\mathbf{K}}, \text{ metric on } \mathbf{P}, \oplus \text{ is nonexpansive}] \\ & \leq \frac{1}{2} \cdot \max\{\max\{d(\varphi(\kappa_1)(\gamma'), \varphi(\kappa_2)(\gamma')) \mid (\varphi, \gamma') \in \text{sched}(\gamma, D)\}, \\ & \quad \max\{d(\kappa_1(\gamma'), \kappa_2(\gamma')) \mid (d_0, \gamma') \in \text{sched}(\gamma, D)\}\} \\ & \quad [\varphi \in \mathbf{D}, \varphi \text{ is nonexpansive}] \\ & \leq \frac{1}{2} \cdot d(\kappa_1, \kappa_2) \end{aligned}$$



Semantics of \mathcal{L}_{SNP} programs

Definition (Semantics of \mathcal{L}_{SNP} programs)

We define $\mathcal{D}[\cdot] : \mathcal{L}_{SNP} \rightarrow \mathbf{P}$ for any $\rho = (D, x) \in \mathcal{L}_{SNP}$ by

$$\mathcal{D}[\rho] = \mathcal{D}[D, x] = \llbracket x \rrbracket(\alpha_0)(\kappa_0)(\gamma_0),$$

where $\kappa_0 = \text{fix}(\Psi_{\mathbf{K}}(D))$, $\gamma_0 = \text{init}_{\Gamma}(D)$ and $\alpha_0 = (N_0, \text{all})$.

- **Haskell implementation** provided in two variants:
 - `Lsnp.hs` - accurate implementation of $\mathcal{D}[\cdot]$; can only run simple \mathcal{L}_{SNP} programs like ρ_1 or ρ'_1 (Π_1)
 - `Lsnp-fin.hs` - stops execution (prunes execution traces) after n steps; can run arbitrary \mathcal{L}_{SNP} programs, including nonterminating and nondeterministic programs

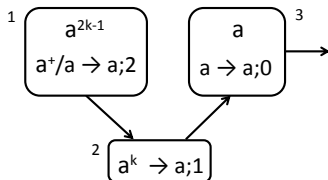
Example: let $\rho_1 = (D_1, x_1)$, $\rho'_1 = (D'_1, x'_1)$ be as before

■ ρ_1 implements **deterministic SN P system** Π_1

- $x_1 = \text{send}((a^{2k-1}), \{N_1\}) \parallel \text{send}(a, \{N_3\})$
- $D_1 =$ neuron $N_0 \{ r_\epsilon \mid \{N_1, N_2, N_3\} \}$,
neuron $N_1 \{ a^+ / [a] \rightarrow a; 2 \mid \{N_2\} \}$,
neuron $N_2 \{ [a^k] \rightarrow a; 1 \mid \{N_3\} \}$,
neuron $N_3 \{ [a] \rightarrow a; 0 \mid \{N_0\} \}$
- $\omega_1 = \{(N_0, []), (N_1, [a, a, a]), (N_2, []), (N_3, [a])\}$
 $\omega_2 = \{(N_0, [a]), (N_1, [a, a, a]), (N_2, []), (N_3, [])\}$
 $\omega_3 = \{(N_0, [a]), (N_1, [a, a, a]), (N_2, []), (N_3, [])\}$
 $\omega_4 = \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$
 $\omega_5 = \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$
 $\omega_6 = \{(N_0, [a]), (N_1, [a, a]), (N_2, [a]), (N_3, [])\}$
 $\omega_7 = \{(N_0, [a]), (N_1, [a]), (N_2, [a, a]), (N_3, [])\}$
 $\omega_8 = \{(N_0, [a]), (N_1, [a]), (N_2, [a, a]), (N_3, [])\}$
 $\omega_9 = \{(N_0, [a]), (N_1, [a]), (N_2, []), (N_3, [a])\}$
 $\omega_{10} = \{(N_0, [a, a]), (N_1, []), (N_2, [a]), (N_3, [])\}$

$$\mathcal{D}[\rho_1] = \llbracket x_1 \rrbracket (\alpha_0) (\kappa_0) (\gamma_0) = \{\omega_1 \omega_2 \omega_3 \omega_4 \omega_5 \omega_6 \omega_7 \omega_8 \omega_9 \omega_{10}\} = \mathcal{D}[\rho'_1]$$

- Our Haskell interpreter `Lsnp-fin.hs` also runs **nondeterministic SN P system** Π_3 [Ionescu, Păun and Yokomori - 2006]; Π_3 computes all natural numbers (> 1)



[Ionescu, Păun and Yokomori – 2006]
SN P system Π_1

Declarative prototyping and denotational specification

```

type D = K -> K
data Den = D0 | D D

type K = Gamma -> P
type Gamma = Bag Sigma
data Sigma =
    Open Xi W
    | Closed Xi W Time W D

type P = [Q]
data Q = Q Omega Q | Epsilon

sem (Aspike a) alpha =
  \k gamma -> k (send a alpha gamma)
sem (Send y xi) alpha =
  sem y (xi `dintersect` alpha)
sem (Par x1 x2) alpha =
  (sem x1 alpha) `par` (sem x2 alpha)

k0 = fix (psiK nDs)
fix :: (a -> a) -> a
fix f = f (fix f)

```

$$\begin{aligned}
 \mathbf{D} &\cong \mathbf{K} \xrightarrow{1} \mathbf{K} \\
 \mathbf{Den} &= \{d_0\} + \mathbf{D} \\
 \mathbf{K} &= \Gamma \xrightarrow{1} \mathbf{P} \\
 \Gamma &= \{\Sigma\} \\
 \Sigma &= \mathbf{Open} + \mathbf{Closed} \\
 \mathbf{Open} &= \Xi \times \mathbf{W} \\
 \mathbf{Closed} &= \Xi \times \mathbf{W} \times \mathbb{N} \times \mathbf{W} \times \frac{1}{2} \cdot \mathbf{D} \\
 \mathbf{P} &= \mathcal{P}_{nco}(\mathbf{Q}) \\
 \mathbf{Q} &\cong \{\epsilon\} + (\Omega \times \frac{1}{2} \mathbf{Q})
 \end{aligned}$$

$$\begin{aligned}
 \llbracket a \rrbracket(\alpha) &= \lambda \kappa . \lambda \gamma . \kappa(\mathit{send}(a, \alpha, \gamma)) \\
 \llbracket \mathit{send}(y, \xi) \rrbracket(\alpha) &= \llbracket y \rrbracket(\xi \mathbin{\frown} \alpha) \\
 \llbracket x_1 \parallel x_2 \rrbracket(\alpha) &= \llbracket x_1 \rrbracket(\alpha) \parallel \llbracket x_2 \rrbracket(\alpha)
 \end{aligned}$$

$$\kappa_0 = \mathit{fix}(\Psi_{\mathbf{K}}(\mathbf{D}))$$

Conclusion and future research

- We offer a **denotational semantics** $\llbracket \cdot \rrbracket$ for an experimental concurrent language \mathcal{L}_{SNP} inspired by the **SN P systems**
 - $\llbracket \cdot \rrbracket$ is designed with **metric domains** and **continuations**
 - Accurately describes the behavior of SN P systems
 - Including time delays and synchronized functioning
 - Offers support for reasoning about the behavior of \mathcal{L}_{SNP}
 - Haskell implementation available from

<http://ftp.utcluj.ro/pub/users/gc/eneia/cmc19>

- In the future we could
 - Study the **abstractness** of denotational vs operational semantics of SN P systems [Ciobanu & Todoran - 2018]
 - Develop **language support and formal verification tools** for SN P systems extended with: dynamical structure, quantitative aspects (stochastic/fuzzy), compositionality



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