

Water computing: A P system variant

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Outline of presentation

- 1 Introduction
- 2 Previous Work
- 3 Control tanks
- 4 Example
- 5 Turing Completeness
- 6 A restricted cP system
- 7 Conclusion

The power of water



Coromandel, New Zealand

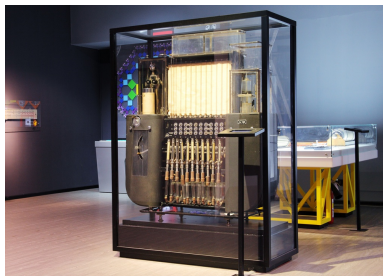
The magical sound,
of the cascading water,
natural beauty

Water Integrator

- First model built in 1936, in USSR; modular model in 1941, standard unified units in 1949-1955



Water Integrator



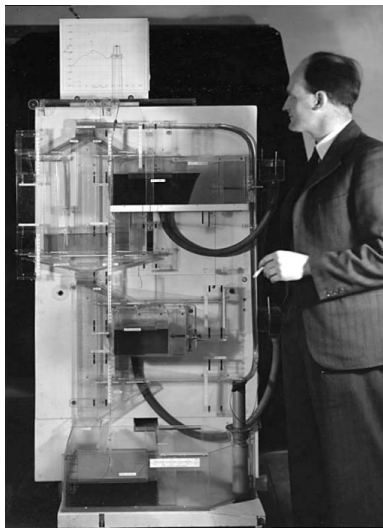
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- Used to solve inhomogeneous differential equations with applications such as: solving construction issues in the sands of Central Asia and in permafrost and in studying the temperature regime of the Antarctic ice sheet

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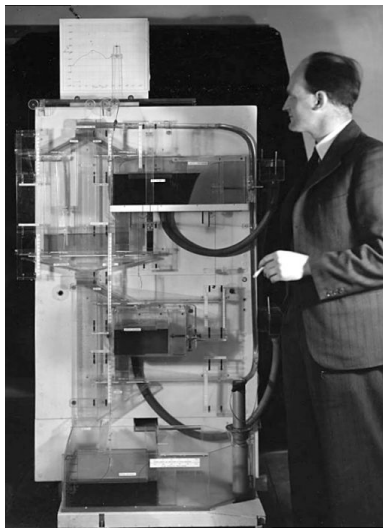
- First model built in 1936, in USSR; modular model in 1941, standard unified units in 1949-1955
- Used to solve inhomogeneous differential equations with applications such as: solving construction issues in the sands of Central Asia and in permafrost and in studying the temperature regime of the Antarctic ice sheet
- Only surpassed by digital computers in the 1980's.

MONIAC (Monetary National Income Analogue Computer)



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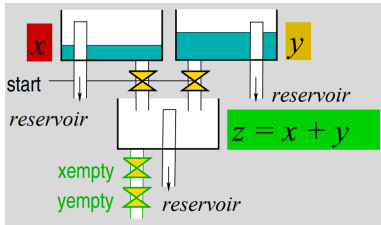
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- First built in 1949 by New Zealand economist Bill Phillips to model the UK economy.
- Built as a teaching aid it was discovered that it was also an effective economic simulator.

Previous Work¹



- No centre of control.
- Water flows if and only if all valves on a pipe are open.
- Water flows between tanks **concurrently**.

¹Thomas Hinze et al. “Membrane computing with water”. In: *J. Membr. Comput.* 2.2 (2020), pp. 121–136.

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Open Problems

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- How to **reset** the system?
- Is the system **Turing complete**?

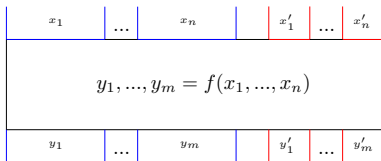
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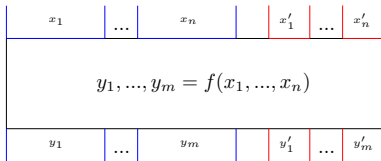
We solve these problems by introducing a set of **control tanks**.

Control tanks

- A control tank for each input and output.

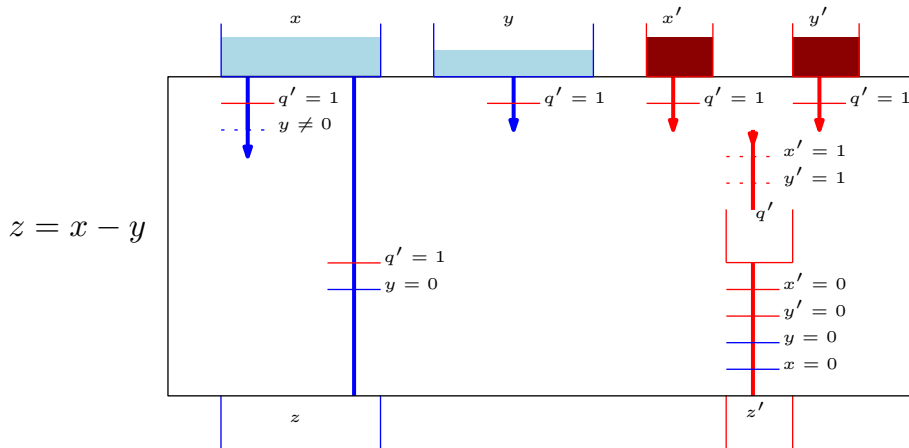


Control tanks

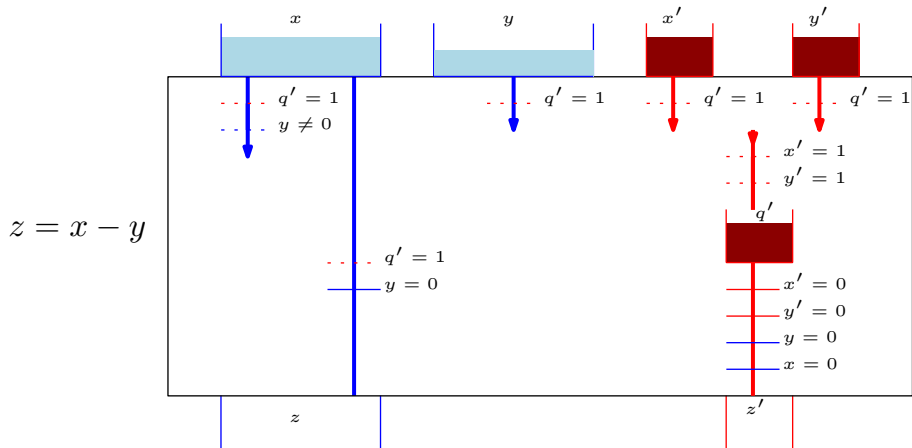


- A control tank for each input and output.
- Start the computation once all control tanks are filled.
- An output is ready when it's control tank is full.

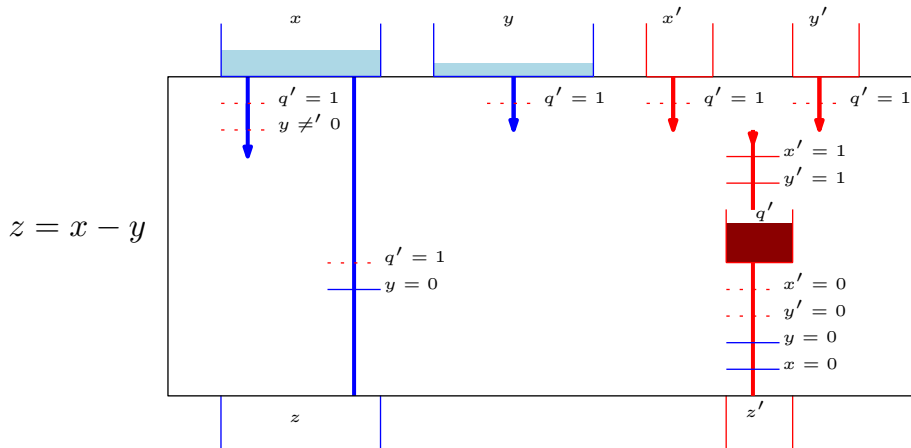
Subtraction



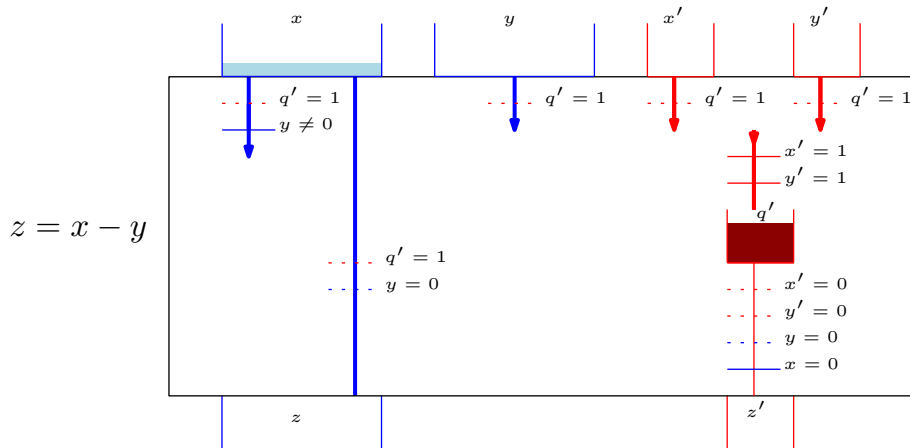
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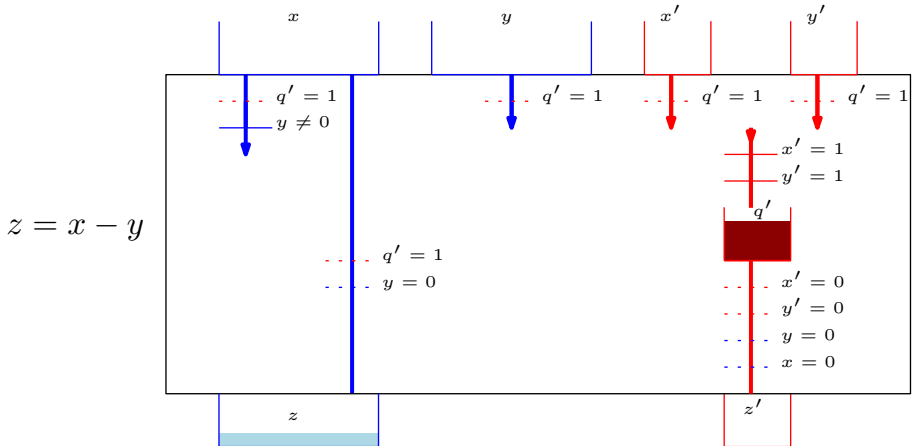
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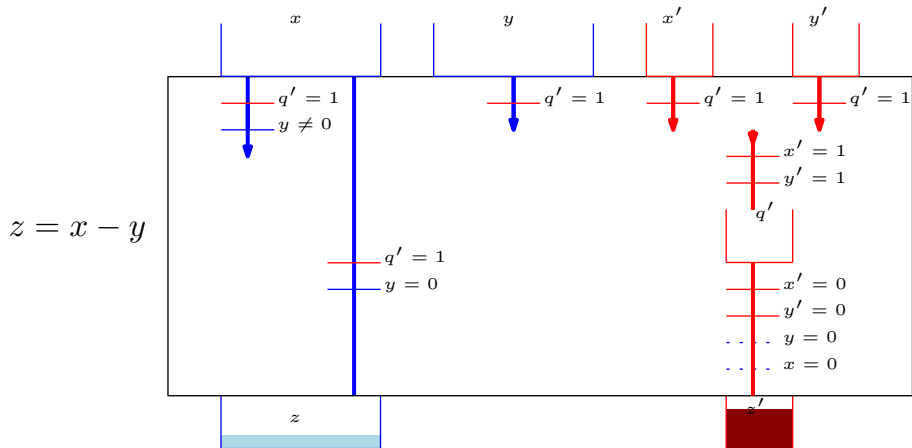
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Subtraction




Primitive Recursion

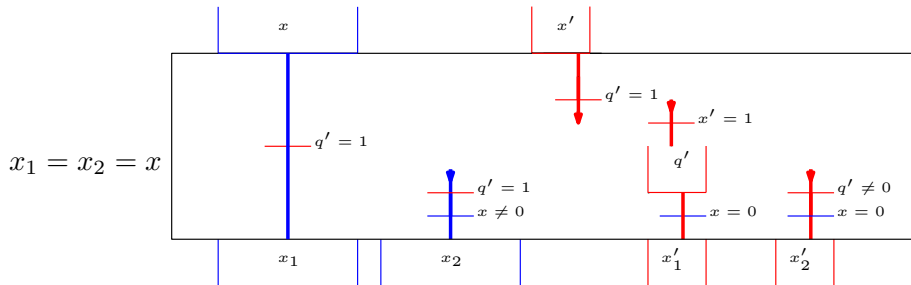
To prove our system can construct all **unary primitive recursive functions** we use the following base functions and closure operators²:

- **Successor function:** $S(x) = x + 1$
- **Subtraction function:** $B(x, y) = x - y$
- **Composition operator:** $C(h, g)(x) = h(g(x))$
- **Difference operator:** $D(f, g)(x) = f(x) - g(x)$
- **Primitive recursion operator:** $P(f)(0) = 0, P(x + 1) = f(P(x))$

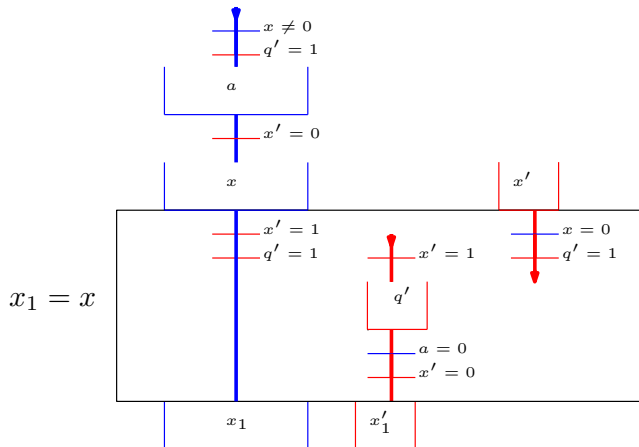
To assist in the proof we also construct two copy functions: inplace $i(x)$ and destructive $c(x)$.

²Cristian Calude and Lila Sântean. "On a theorem of Günter Asser". In: *Mathematical Logic Quarterly* 36.2 (1990), pp. 143–147. 

Destructive copy $x_1 = x_2 = x$

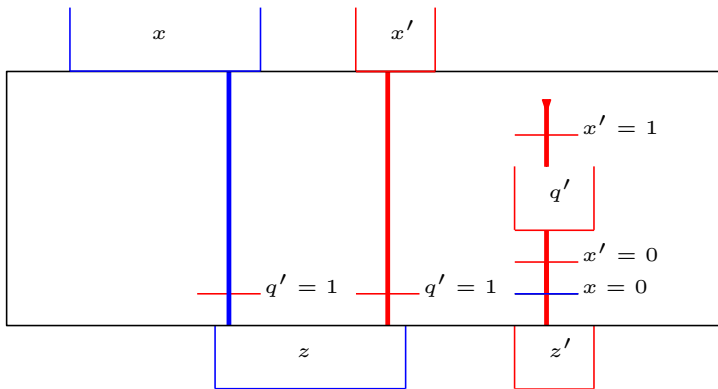


Inplace copy $x_1 = x$

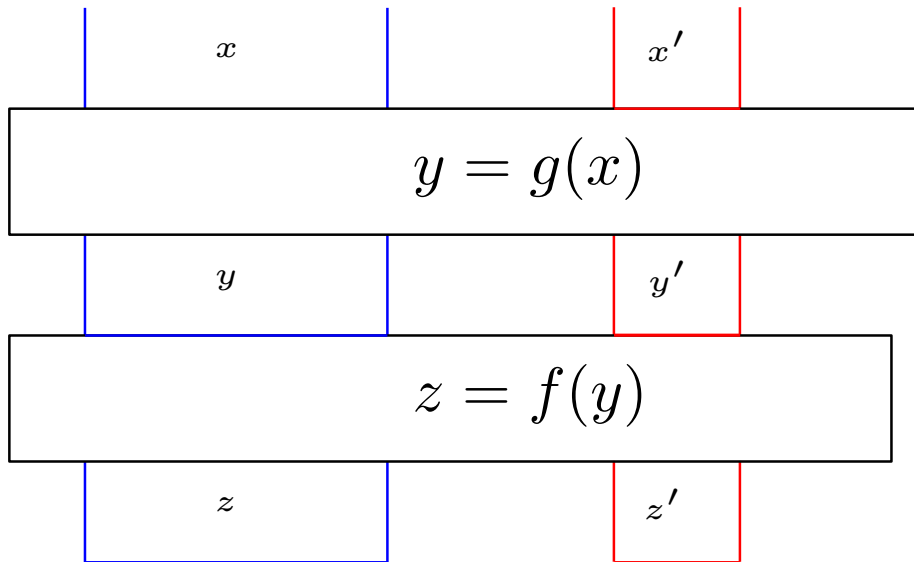


Successor function $S(x) = x + 1$

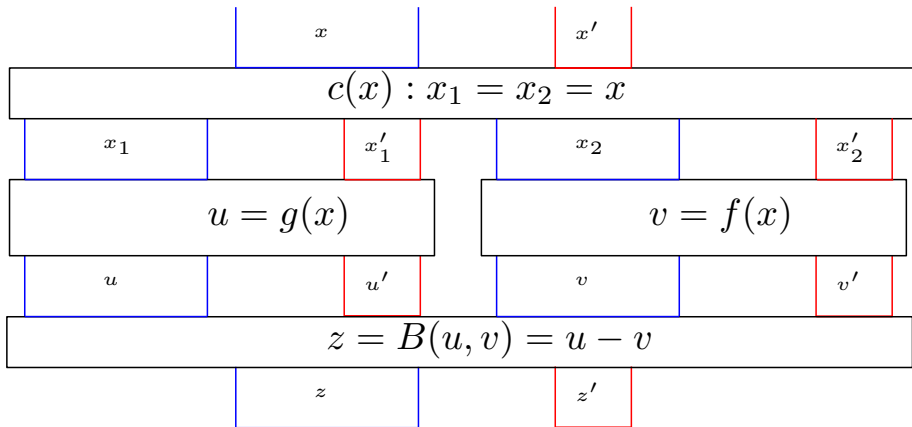
$$z = x + 1$$



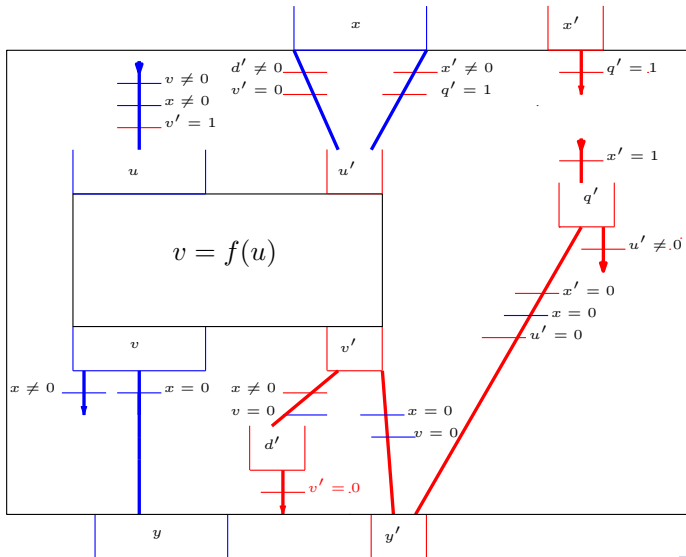
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Primitive recursion operator $P(f)(0) = 0$,
 $P(x + 1) = f(P(x))$

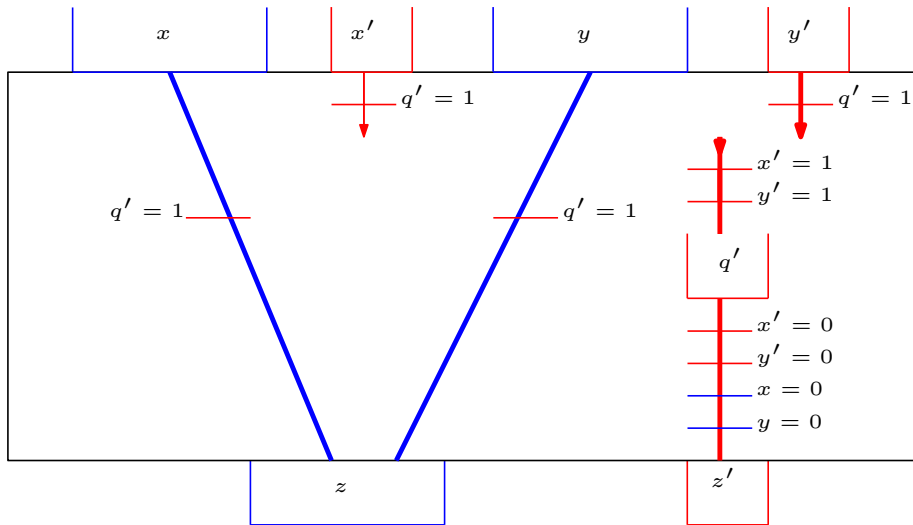


To prove Turing completeness we require that our system can construct the unary primitive recursive functions as well as³:

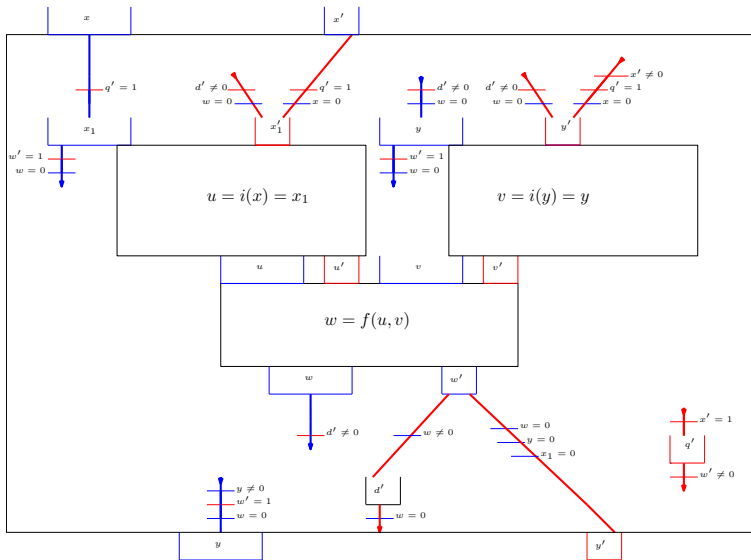
- **Addition function:** $A(x, y) = x + y$
- **μ operator:** $\mu_y(f)(x, y) = \min_y \{f(x, y) = 0\}$

³Julia Robinson. "General recursive functions". In: *Proceedings of the american mathematical society* 1.6 (1950), pp. 703–718.

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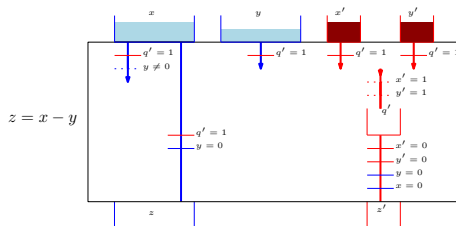
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- cP systems have a set of rules for changing the content in the subcells. Similarly we have a set of valves and pipes.
- cP systems are able to create and consume subcells whereas in our system we cannot create and consume tanks.
- Using the similarities we are able to construct cP system-like rules which don't contain creating or consuming of subcells.

Rules for subtraction



$s_1 q()$	\rightarrow	$s_2 q(1)$		$c_x(1) c_y(1)$	(1)
$s_2 c_x(1)$	\rightarrow	$s_2 c_x()$		$q(1)$	(2)
$s_2 c_y(1)$	\rightarrow	$s_2 c_y()$		$q(1)$	(3)
$s_2 v_x(X1)$	\rightarrow	$s_2 v_x(X)$		$q(1) v_y(.1)$	(4)
$s_2 v_y(Y1)$	\rightarrow	$s_2 v_y(Y)$		$q(1)$	(5)
$s_2 v_x(X1) v_z(Z)$	\rightarrow	$s_2 v_x(X) v_z(Z1)$		$q(1) v_y()$	(6)
$s_2 q(1) c_z()$	\rightarrow	$s_3 q() c_z(1)$		$c_x() c_y()$	(7)

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- We have demonstrated how termination can be detected, as well as how to combine different functions without an exponential explosion of the number of valves.
- We have given a brief description on how our water tank system is a restricted version of cP systems.

- Being able to run a function without all of the controls being filled.

Future Work

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Future Work

- Being able to run a function without all of the controls being filled.
- Solving practical problems with the system.
- Using the system to model biological systems.
- Constructing a programmable universal water computer.

Questions



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- Thank you for listening.

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- Any questions?